

# **2018 Workshop on Autonomy for Future NASA Science Missions**

**October 10-11, 2018**



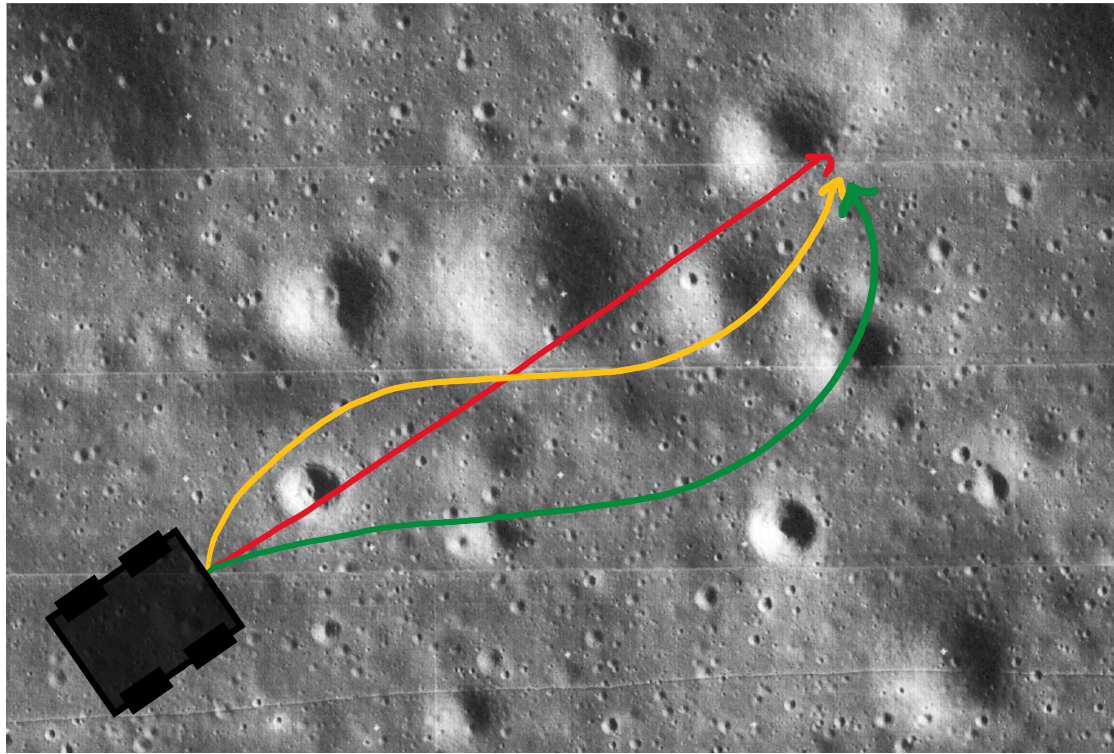
## **Cost Function Design for Planning in Robotic Systems**

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University of California, Berkeley

# Cost Function Design



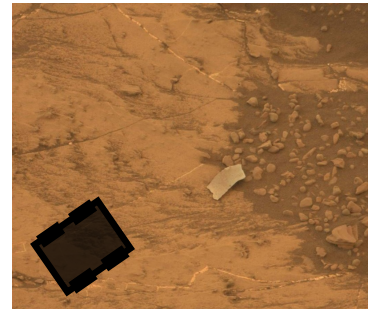
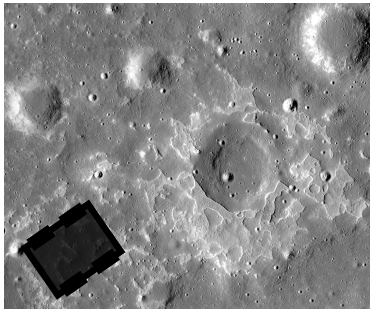
- How do we specify a cost function in planning?



# Proposed Framework



- Consider a diverse set of environments (terrain, weather conditions, etc.)

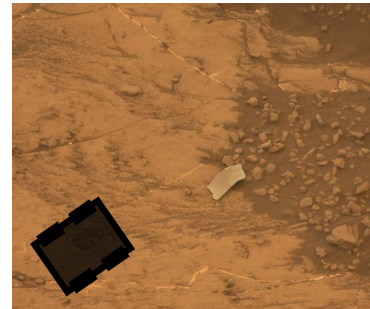
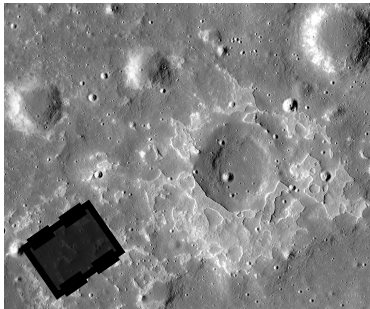




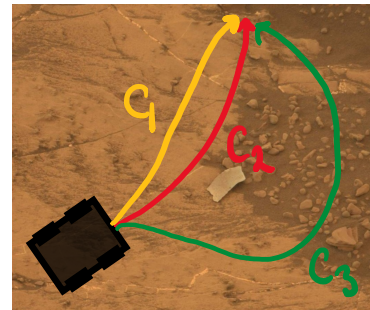
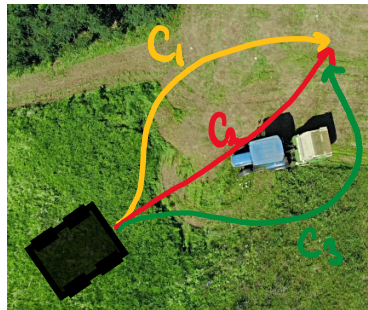
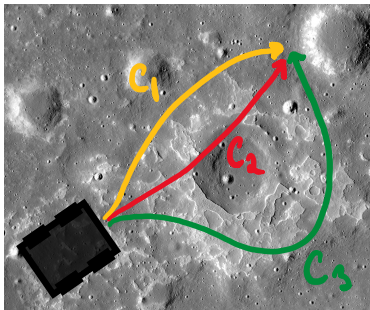
# Proposed Framework



- Consider a diverse set of environments (terrain, weather conditions, etc.)



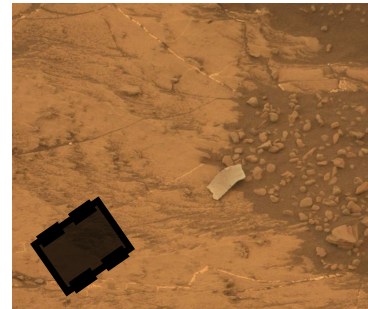
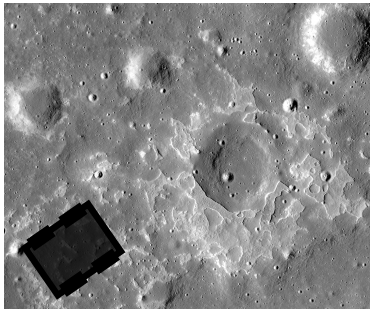
- Specify a *separate* cost function for each



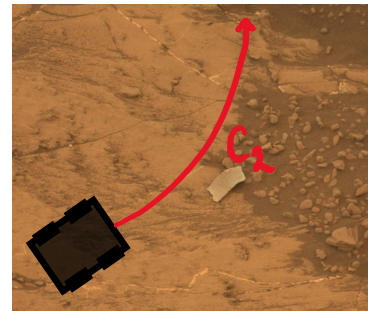
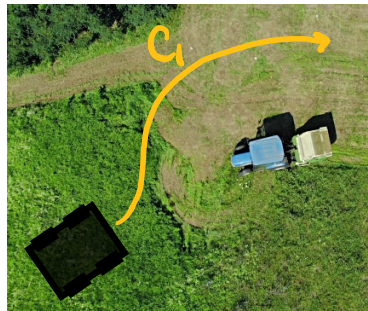
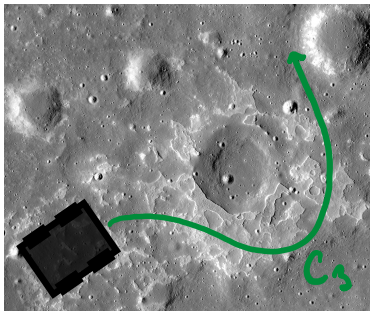
# Proposed Framework



- Consider a diverse set of environments (terrain, weather conditions, etc.)



- Specify a *separate* cost function for each



$P(c)$