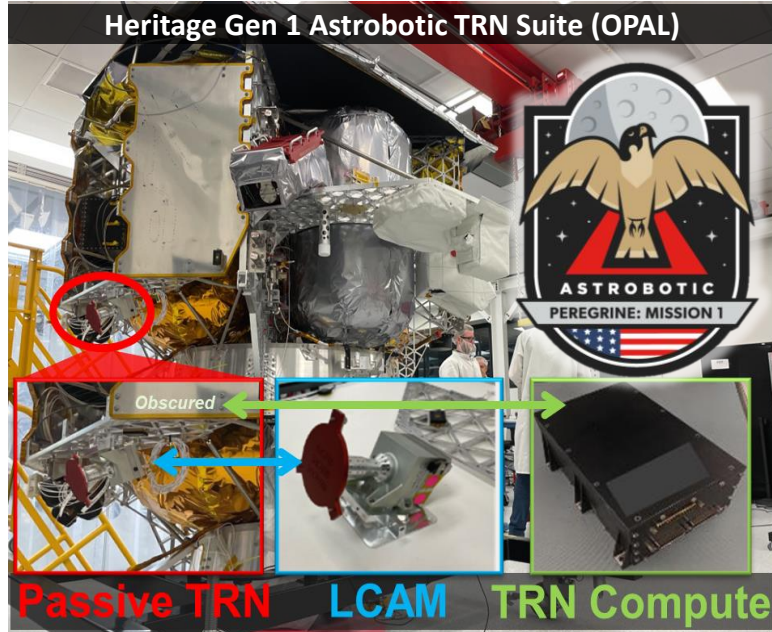


## HIGH-MATURITY, HIGH-PERFORMANCE NAVIGATION FOR PLANETARY SPACECRAFT

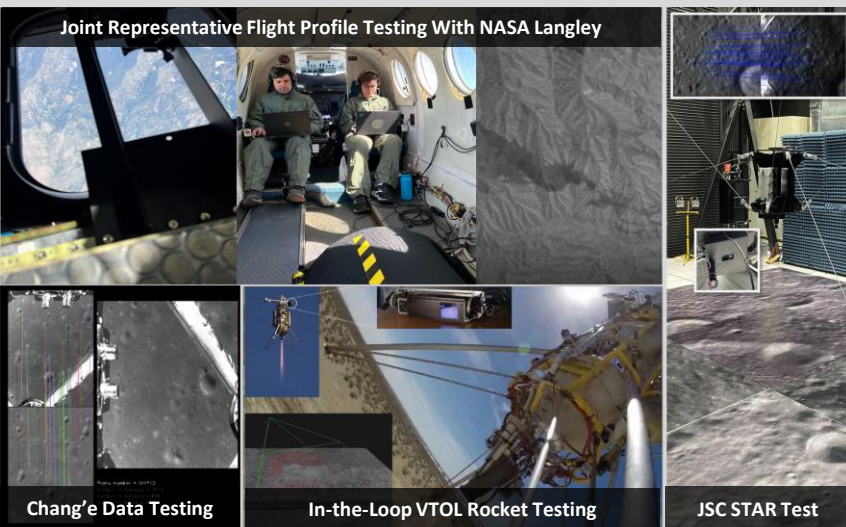
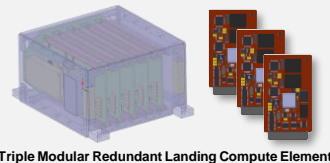
### SAFER, MORE PRECISE LANDINGS

Astrobotic has developed visual terrain relative navigation to enable precise and safe planetary landings on the Moon, Mars, and beyond. We were the first commercial company to use TRN and hazard detection to guide a suborbital rocket to a safe landing site. Our Generation 1 TRN system is integrated onto the Peregrine Mission 1 lunar lander after a full design, space qualification, flight test, and V&V campaign, including IV&V from JPL; our Gen. 2 systems adds additional robustness/assurance for Griffin Mission 1, which will deliver SMD's high-priority VIPER lunar rover. Our TRN consists of a camera element and a compute element. The camera captures images of the planetary body and relays them to the compute element, where our software compares them to Astrobotic-generated maps of the planetary surface to determine the precise pose of the camera, which is fed to the landers GNC, providing low-latency, autonomous DDL navigation.



**Astrobotic Gen. 2 TRN System**  
Used for >\$750M Griffin / NASA VIPER Landing

Adds additional robustness functionality and flight testing



### MATURE, FLIGHT-TESTED SOLUTION

Our extensive testing campaign includes:

- Full aerial flight test over DDL-representative flight profile with flight-representative TRN suite
- In-the-Loop navigation with VTOL Rockets
- SWIL testing with simulated and actual landing video
- Testing at multiple JSC sensor testbeds
- JPL IV&V of software; independent assessment from senior NASA SMEs; third-party map certification

### ASTROBOTIC TRN FEATURES

-  Complete TRN Solution
-  Safe, Precise Planetary Landings
-  Low Size, Weight, & Power (swaP)
-  Simplified Spacecraft Integration
-  Engineering Model and Support Hardware Available
-  EDL/DDL Software Tools and Analysis Support
-  Full Mission Lifecycle Support
-  Experienced Team