



National Aeronautics and
Space Administration

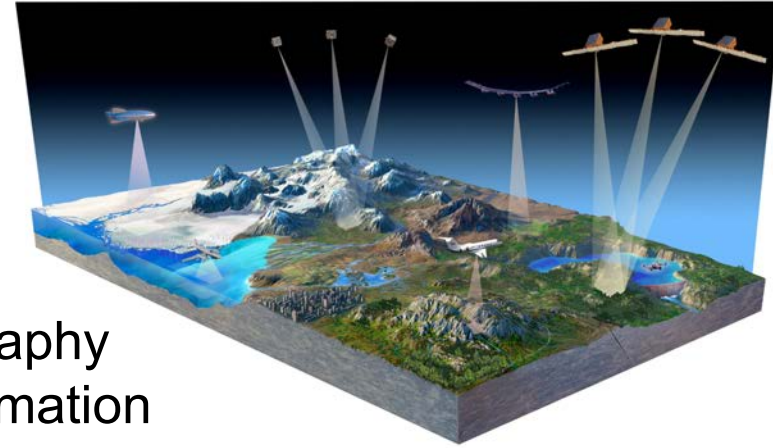
Jet Propulsion Laboratory
California Institute of Technology
Pasadena, California

Multi-Sensor Multi-platform Surface Topography and Vegetation Structure Data Fusion Information System (STV-FIS)

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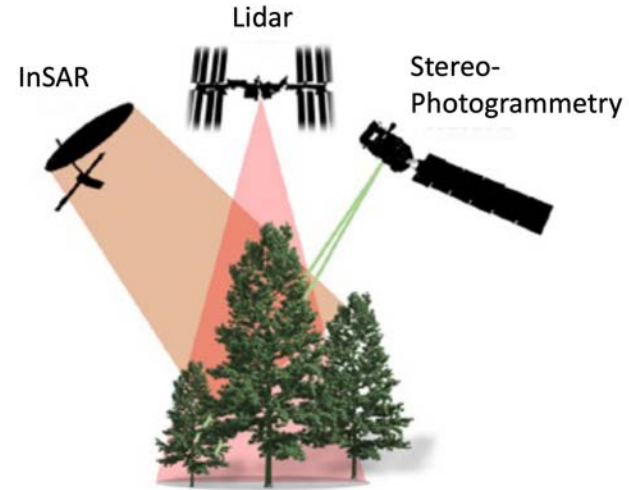
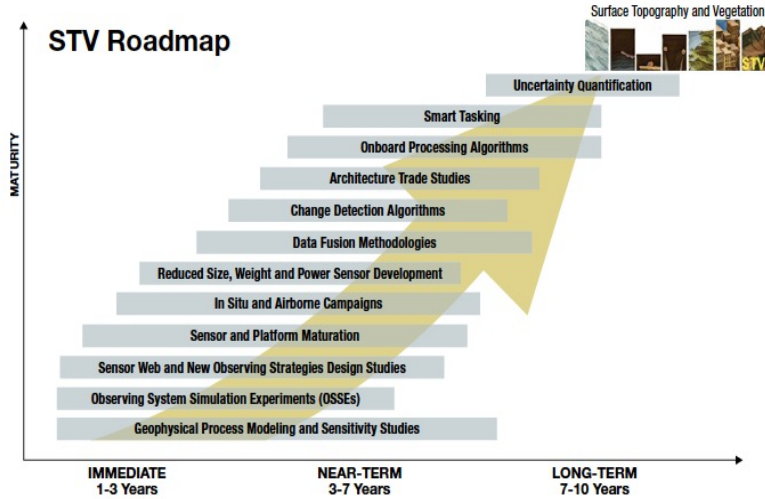
Type of Observing Platform



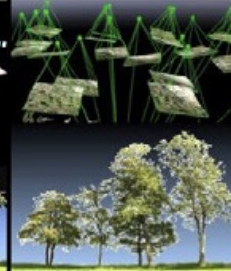
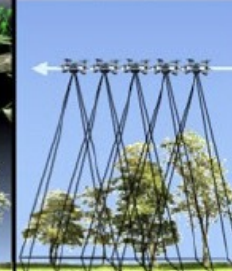

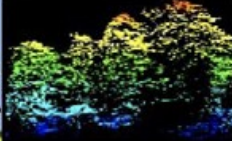
Radar and Lidar

Science Topic Focus

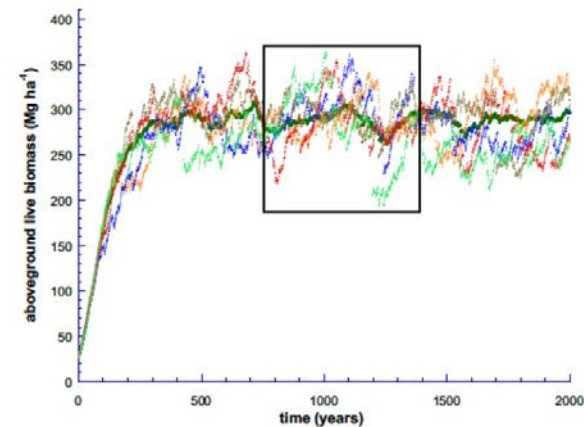
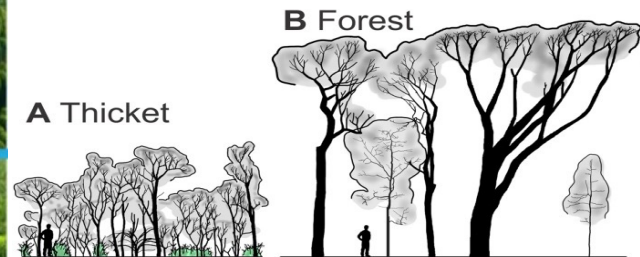
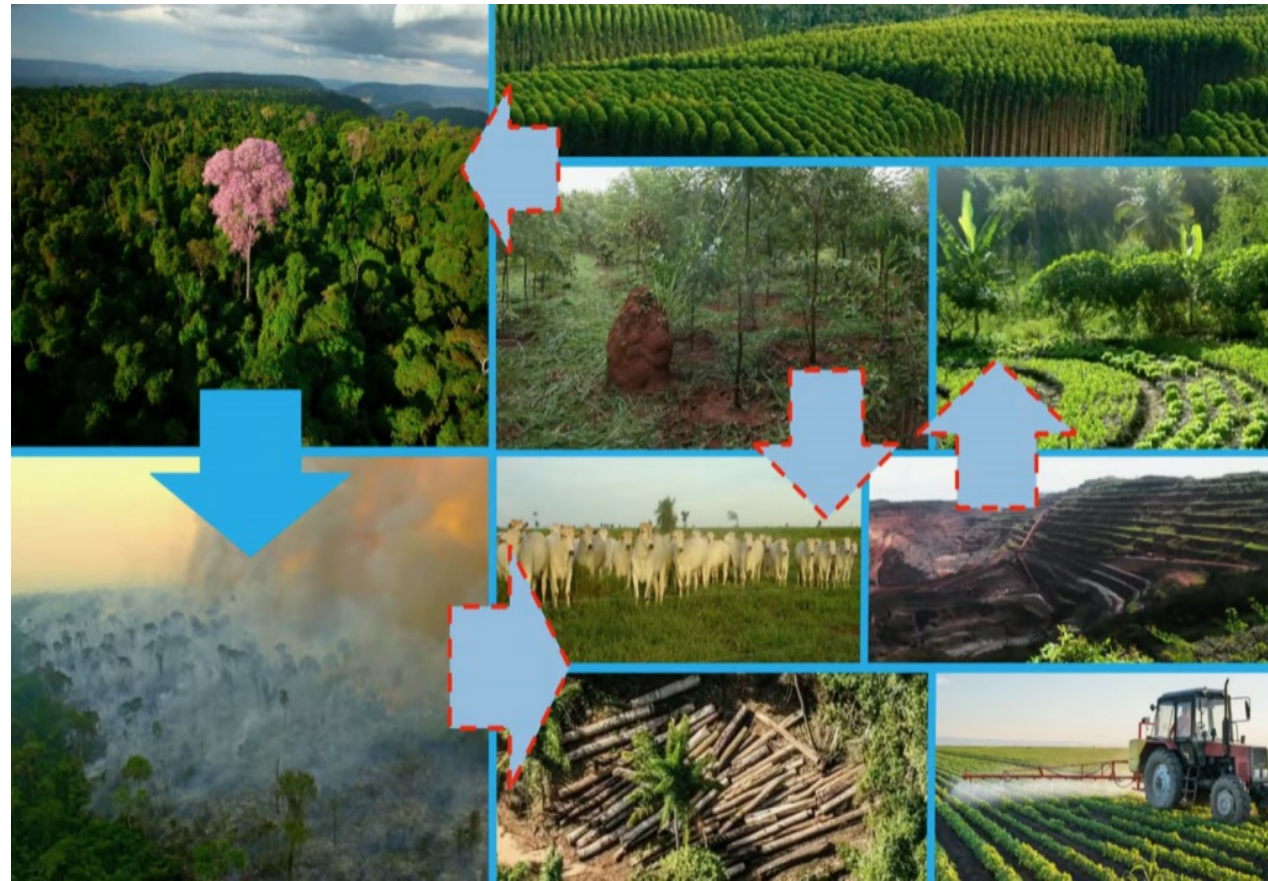
Vegetation Structure and Topography

STV Measurements



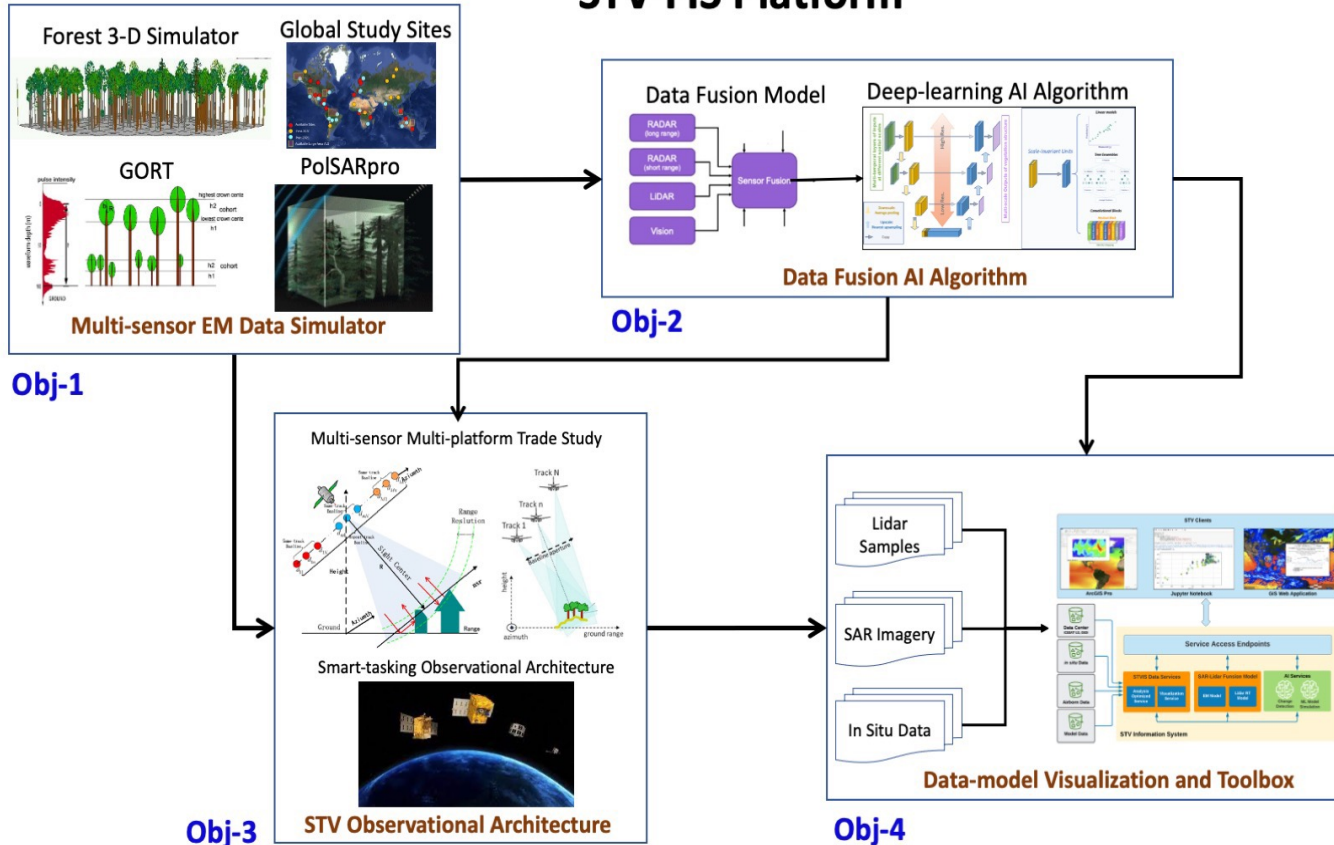
Rotating platform One camera Two or three view angles	Nadir platform Two or three cameras Two or three view angles	Multiple platforms and/or times Two or more view angles	Nadir platform One camera Overlapping images	Nadir platform Many cameras Many view angles	Products
					Image correlation point cloud (colored by height) from which gridded DSM or DTM can be produced 

Science of Vegetation



Graphical Project Summary

STV-FIS Platform



- *Obj-1. Develop a multi-sensor (Radar and Lidar) data fusion platform based on 3D EM simulations*
- *Obj-2. Develop Artificial Intelligence (AI) model-data analytics change detection, and uncertainty assessment.*
- *Obj-3. Simulate a dedicated data fusion observing system for multi-sensor and multi-platform*
- *Obj-4. Integrate model and data fusion within a visualization system and on-line analytical toolbox*

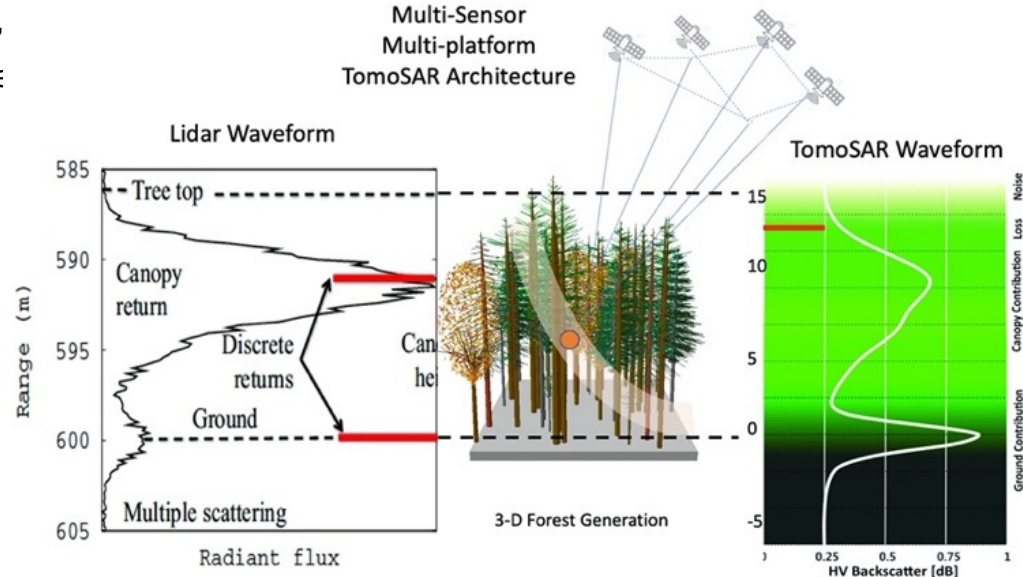
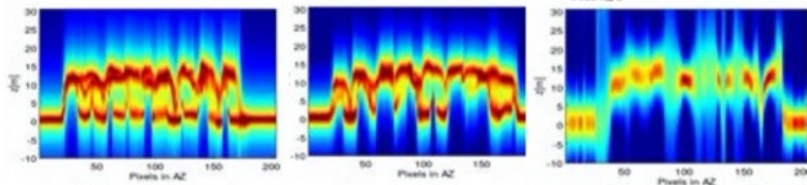
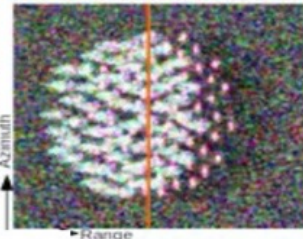
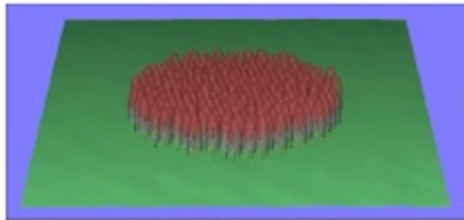
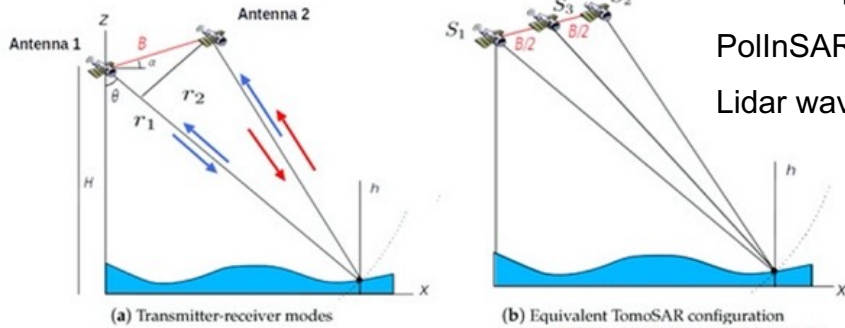
Methods

Forest Canopy Simulator

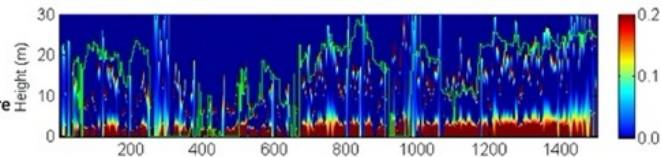
Multi-frequency SAR (P-, L-, C-band)

PolInSAR,

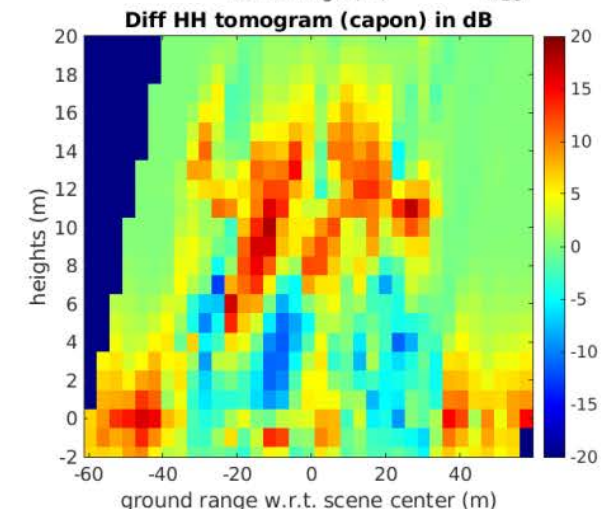
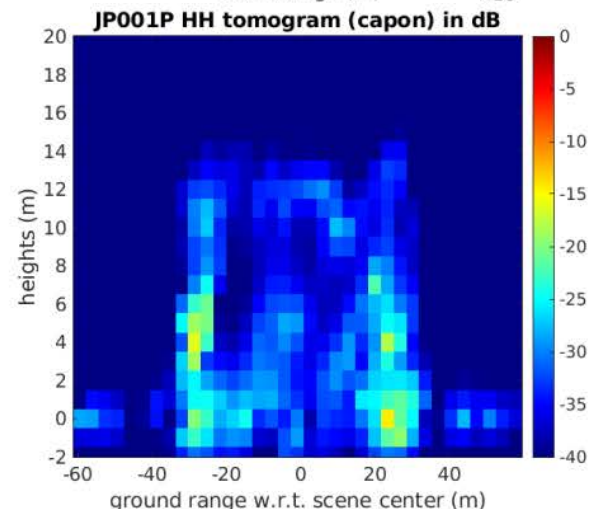
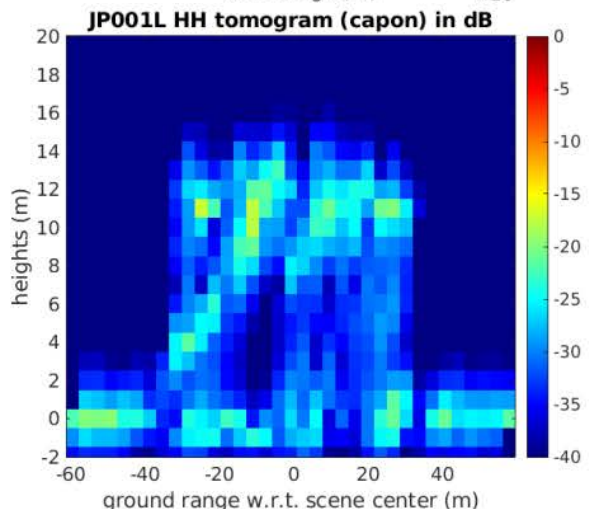
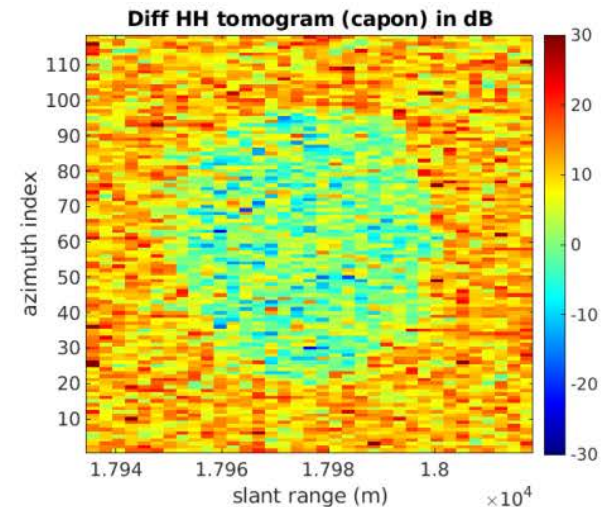
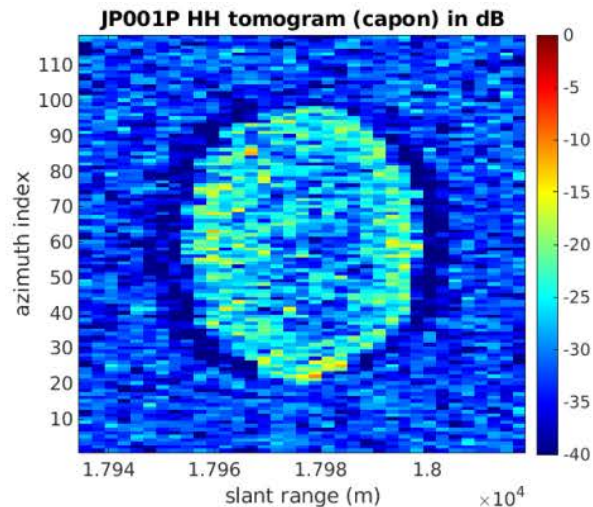
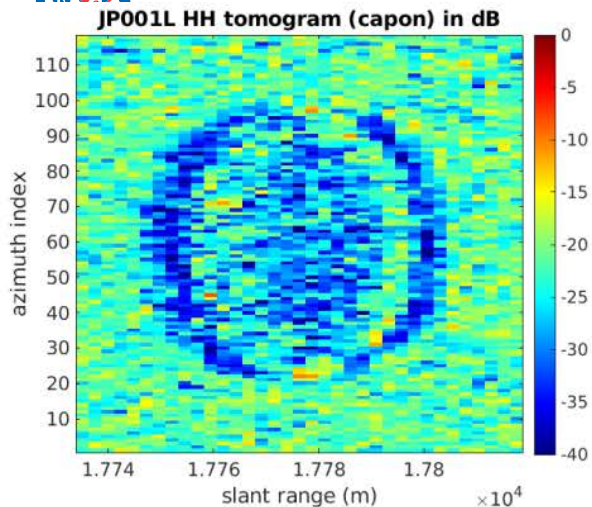
Lidar wave



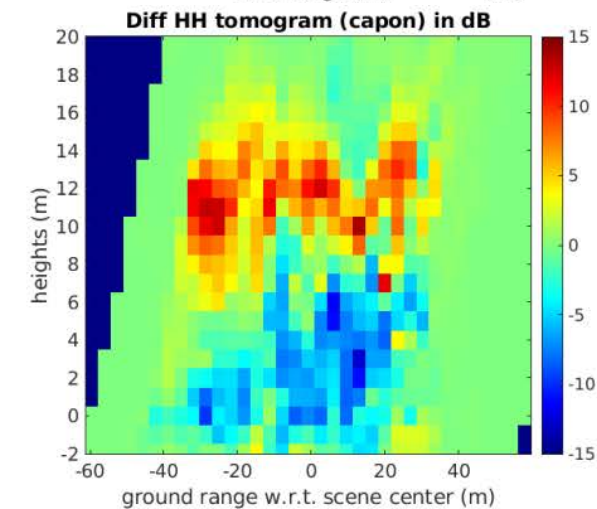
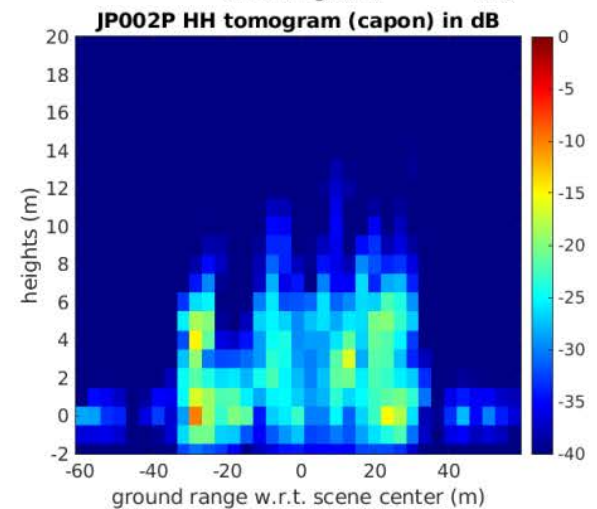
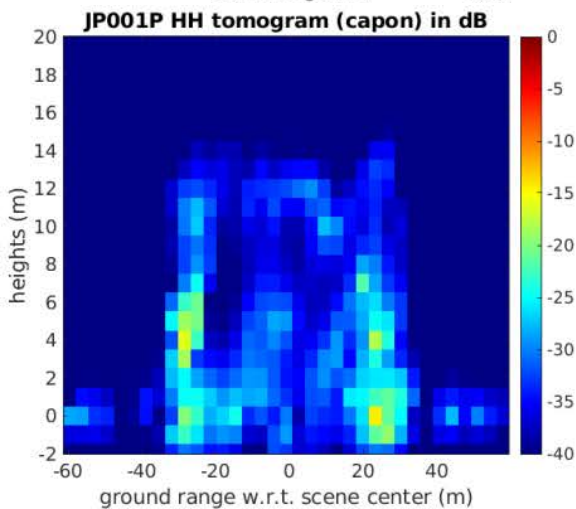
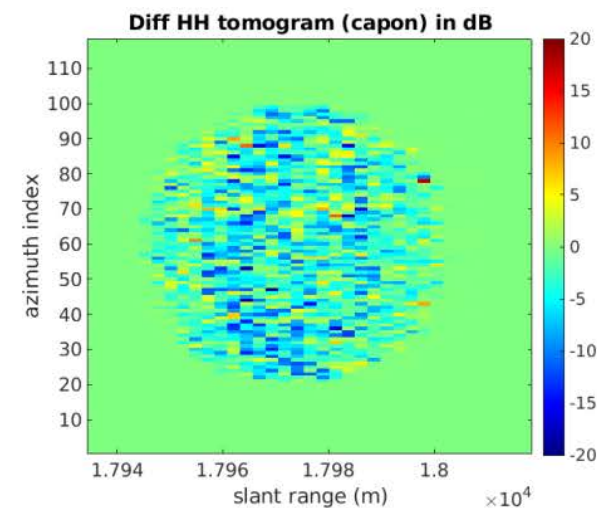
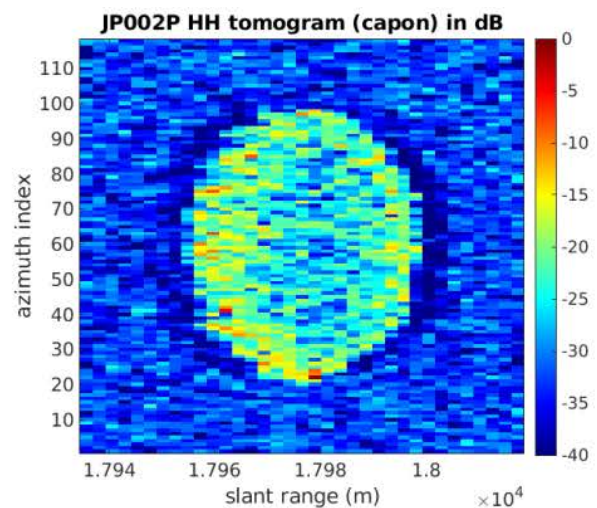
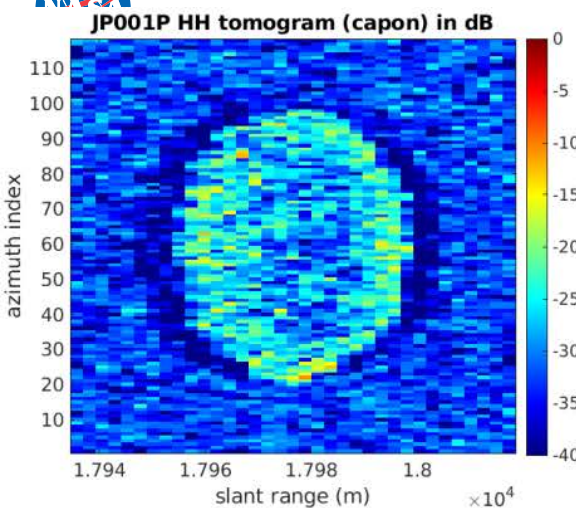
TomoSAR 3-D Vegetation structure



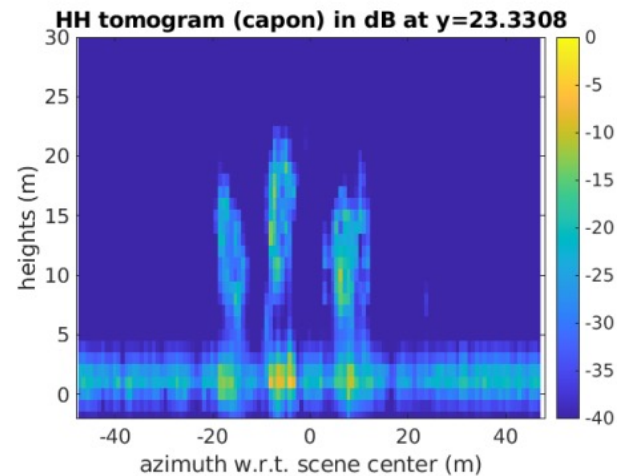
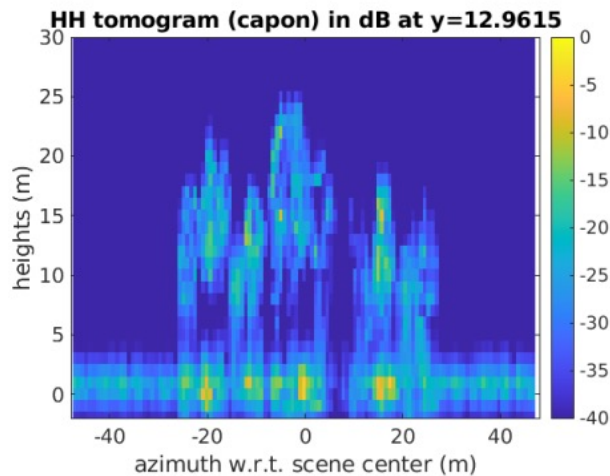
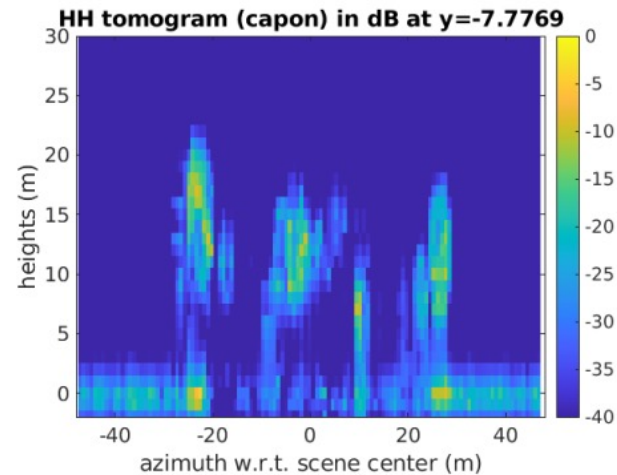
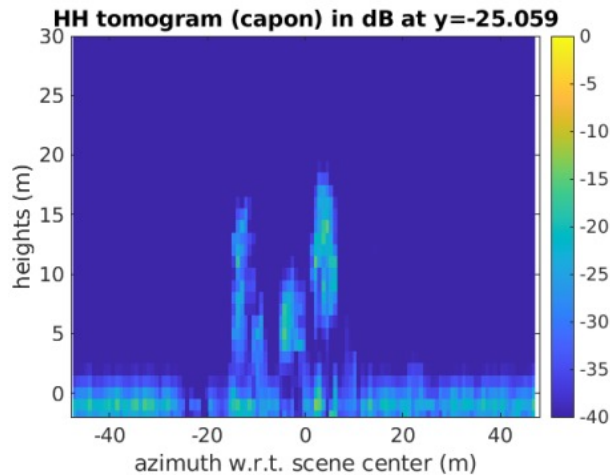
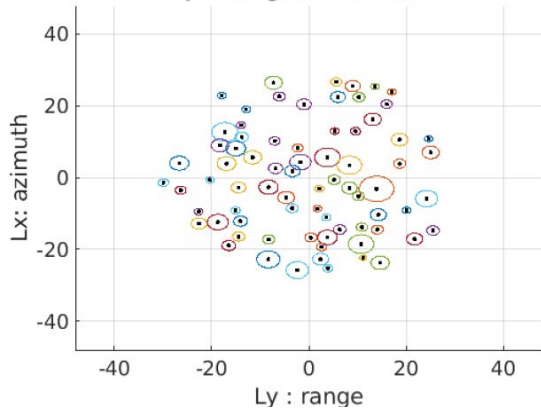
Compare same Jack Pine forest at two different frequencies



Compare Jack Pine forest where number of primary and secondary branches are 20% for P band

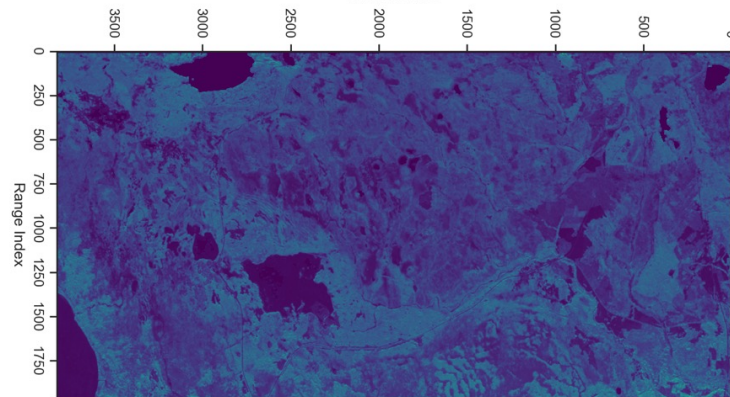
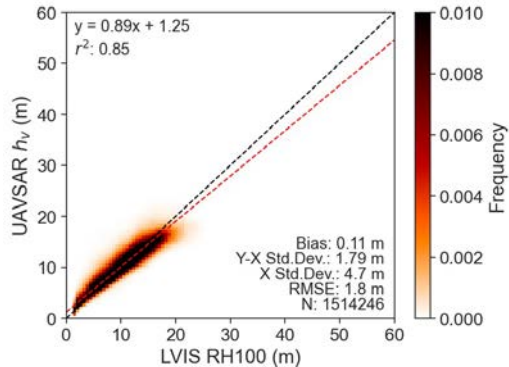
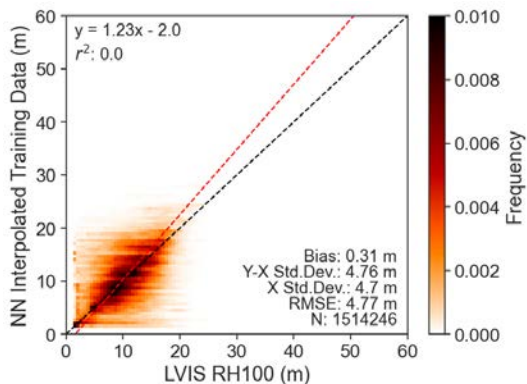
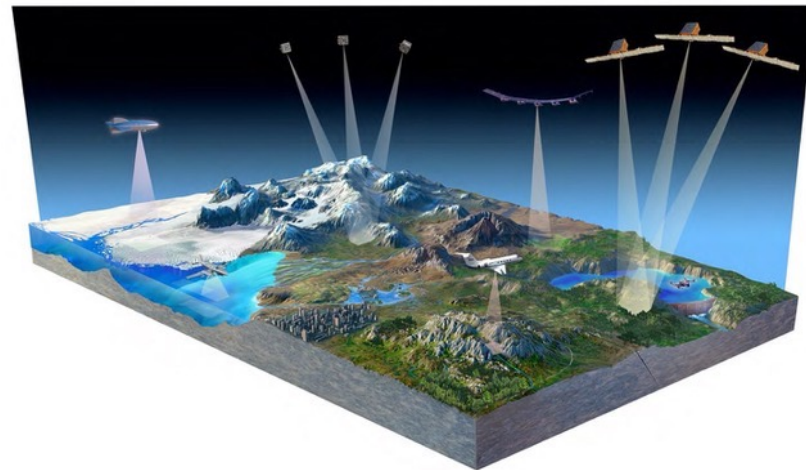


plotting tree crowns



Data Fusion Performance Model

- ML Data fusion work has started using UAVSAR and Lidar data during the the AfriSAR field campaign and extended to the recent data collected in California
- Deep-learning networks were trained using different UAVSAR scenes and different interferometric baselines within each scene.
- The work was build on previous work and the SR&TD results without any model inversions.
- The trained networks estimate canopy height directly from the input features.



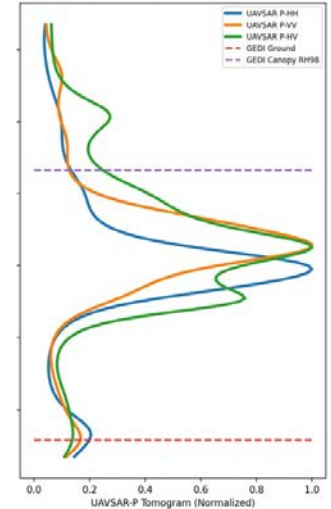
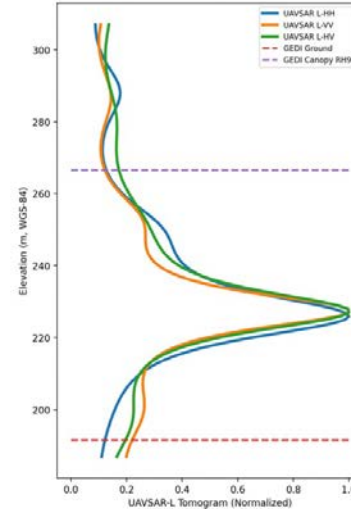
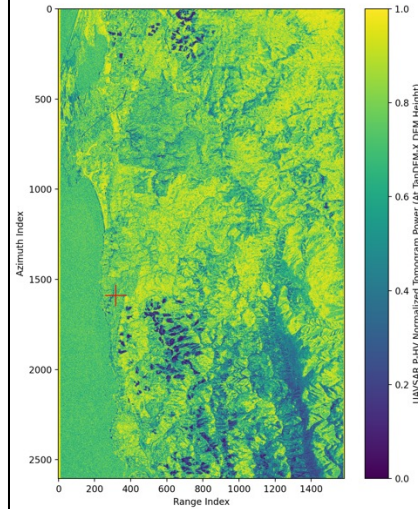
Milestone #1 Status

Milestone: Update UAVSAR phase calibration software and other processing tools in order to produce better calibrated UAVSAR SLC stacks for available L- and P-band data. Add support for P-band UAVSAR data to Kapok software. (Proposed Completion: January 31, 2023)

Status: Complete

Sub-Tasks:

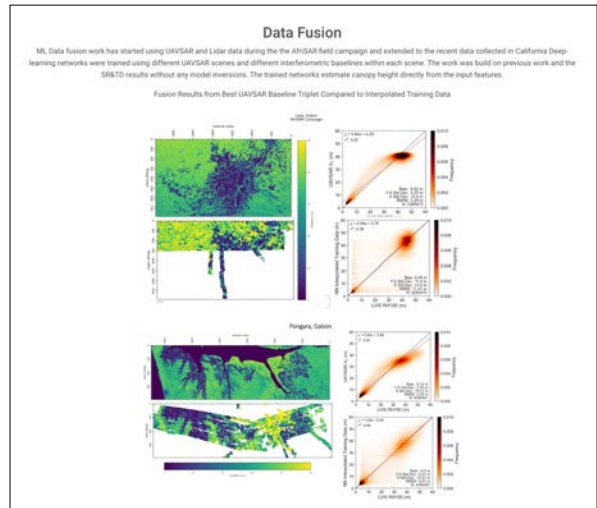
1. Update UAVSAR phase calibration software to support longer, multi-segment L- and P-band data (Complete)
2. Add support for P-band UAVSAR data to Kapok PolInSAR/TomoSAR post-processing software (Complete)




Comparing UAVSAR tomogram power profiles to GEDI data shows complex (multiple peak) structure of tall redwood forests. Example profile has GEDI canopy height of 75 m. Ground peak can be observed at P-band but not L-band

Public-facing Website

- One-stop web presence about our project
- Background information
- Latest research
- Latest tools and visualizations
- Access to public repo to the project's jupyter notebook




 Surface Topography and Vegetation
 Structure Data Fusion Information System



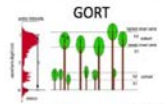
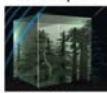
Home Project Data Tools News Team

Multi-Sensor Multi-platform Surface Topography and Vegetation Structure Data Fusion Information System

This project is supported via NASA's Earth Science Technology Office from the Decadal Survey Incubation program.

The STV data fusion information system (STV-FIS) will enable design and implementation of multi-sensor, multi-platform architectures and will address key STV gaps by:

Developing a multi-sensor (Radar and Lidar) data fusion platform based on 3D EM simulations

Forest 3-D Simulator Global Study Sites


 GORT PolSARpro


Multi-sensor EM Data Simulator

<https://ideas-digitaltwin.jpl.nasa.gov/stvfis/>