Lunar Discovery and Exploration Program (LDEP) Update

May 5, 2024

- Plans/Strategies
  - Implementation plan for Integrated Lunar Science Strategy (NASA) – issued for community comment
  - Community Science Definition Team: objectives for Endurance-A Mission (South Pole-Aitken Basin sample return)
  - NASA Moon2Mars Architecture Concept Review 23 – Nov 2024
  - NASA Architecture Definition Document (ADD) – Feb 2024
- Competitive Solicitations
  - Artemis III Deployed Instruments call (A3DI)
    - selections spring 2024
  - PRISM4 (Stand Alone Site Agnostic (SALSA) instruments call)
    - Draft call for community comment spring 2024
  - Planning: A4DI
  - Planning: LTV instruments
  - Planning: A4 Hand-Held Instruments
  - LROC: imaged CH-3, SLIM, IM-1 landing sites
  - LOLA: lased CH-3 Vikram LRA
  - KPLO/Danuri/ShadowCam
    - LDEP now funding ShadowCam/DSN Ops
  - Artemis II
    - Artemis II Lunar Observation Campaign (ALOC) [Lead: Young/NASA GSFC] (Artemis II)
- PRISM1 instrument suites in development:
  - Farside Seismic Suite (FSS) [Panning/JPL] (CP-12)
  - Lunar Interior Temperature and Materials Suite (LITMS) [Grimm/SwRI] (CP-12)
- PRISM2 instrument suites in development:
  - Lunar Vulkan Imaging and Spectroscopy Explorer (LunarVISE) [Donaldson-Hanna/UCF] (CP-21)
  - Lunar Explorer Instrument for Space Biology Applications (LEIA) [Settles/NASA ARC] (CP-22)
- PRISM3 instrument suite in development:
  - Dating an Irregular Mare Patch with a Lunar Explorer (DIMPLE) [Anderson/SwRI] (CP-32)
- Artemis III Geology Team selected (A3GT)
  - Earth-based Artemis III Geologists for Lunar Exploration (EAGLE) [Denevi/APL] (Artemis III)
- CLPS delivery competitions
  - Next: CP-22 (LEIA + others) to South Pole
    - CLPS company proposals in evaluation
  - Then: CP-21 (LunarVISE + others) to Gruithuisen Domes
- VIPER Assembly; GM-1 response to PM-1
  - Lunar Trailblazer env testing -> storage; rideshare on IM-2 (Nov 2024) [Ehlmann/CalTech]
TO2-AB
PM-1
Did Not Land
Peregrine Lander

TO2-IM
IM-1
Landed 2/22
No Power 2/29
Nova-C Lander

TO19D
Blue
Ghost 1
Blue Ghost lander

TO20A – VIPER
GM-1
PM-1 FRB Results
NASA Evaluation
Griffin Lander

PRIME-1
IM-2
Nova-C Lander

CP-11
IM-3
Nova-C Lander

CP-12
TBA
Series-2 Lander

CS-3 & CS-4
Blue
Ghost 2
Blue Ghost Lander
By blocking the Sun with one of Peregrine’s struts, Astrobotic engineers were able to capture this striking view of the crescent Earth. The company’s CEO, John Thornton, identified this photo as his favorite surprise of the mission. Credit: Astrobotic.
**Peregrine Ion-Trap Mass Spectrometer (PITMS):**
gather data about the **presence and variability of the OH, H2O, noble gases, nitrogen, and sodium** compounds that are released from the Moon's regolith and travel through the exosphere over the course of the long lunar day.

**Neutron Spectrometer System (NSS):**
determine the **abundance of hydrogen-bearing** materials and the bulk regolith **composition** at the landing site **up to a depth of three feet below the surface** and measure any variations during the diurnal cycle.

**Lunar Retroreflector Array (LRA):**
function as a permanent **location marker on the Moon** for decades to come.

**Near Infrared Volatile Spectrometer System (NIRVSS):**
measure **surface and subsurface hydration** (H$_2$O and OH) as well as CO2 and methane, while simultaneously mapping **surface morphology and surface temperatures**.

**Linear Energy Transfer Spectrometer (LETS):**
quantify **radiation** at the lunar surface from **Galactic Cosmic Rays**—high-energy particles that zip into our solar system from distant points in the galaxy—and from space weather caused by the Sun.
IM-1
Stereo Cameras for Lunar Plume-Surface Studies (SCALPSS): record effects of engine plume interactions with the lunar surface to understand how the landing event changes the lunar surface topography.

Radio Wave Observations at the Lunar Surface photoElectron Sheath (ROLSES): measure the density of the electrons ejected from lunar dust by photons of sunlight and detect radio emissions from the Sun, Jupiter, and Earth's aurora to characterize the south polar environment of the Moon.

Navigation Doppler Lidar (NDL): laser-based sensor that helps the spacecraft determine how far above the surface it is and how fast it is moving, to help the spacecraft land precisely.

Lunar Retroreflector Array (LRA): a permanent location marker on the Moon for decades to come.

Lunar Node-1 (LN-1): transmit navigation and communication radio signals to guide incoming/outgoing vehicles with precision to reduce the amount of fuel required for future safe landings.

Radio Frequency Mass Gauge (RFMG): space-age gauge to measure the amount of cryogenic propellant in spacecraft in zero gravity, to monitor propellant reserves and save fuel during transit and landing.
Intuitive Machines' Odysseus lander is shown shortly before touching down on the Moon.
Image of Odysseus landing on the Moon with one landing leg broken. The darker area is lunar regolith being disturbed by the engines, which are still firing. Credit: Intuitive Machines
The Odysseus lander on the surface of the Moon. The dark oval area to the left of the gold-covered helium tank is a crater. The near rim is only about 500 meters away. Credit: Intuitive Machines
EXPLORE MOON to MARS
MOON LIGHTS THE WAY